

Camera Selection Criteria

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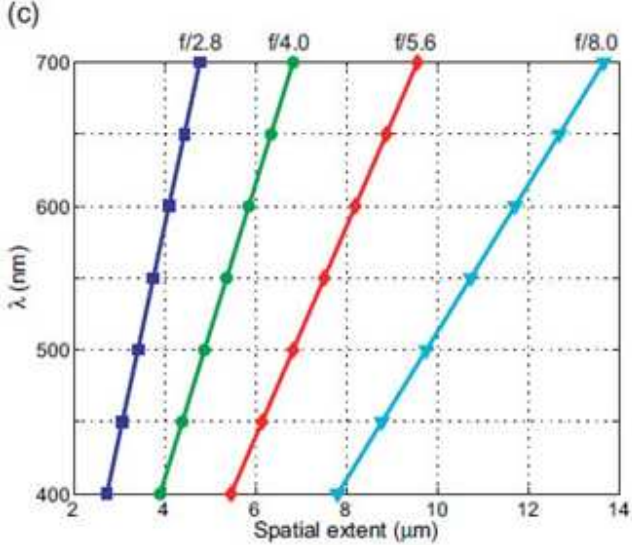
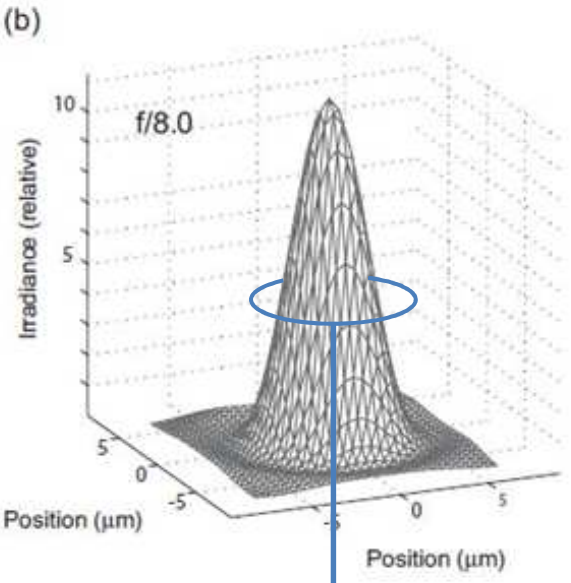
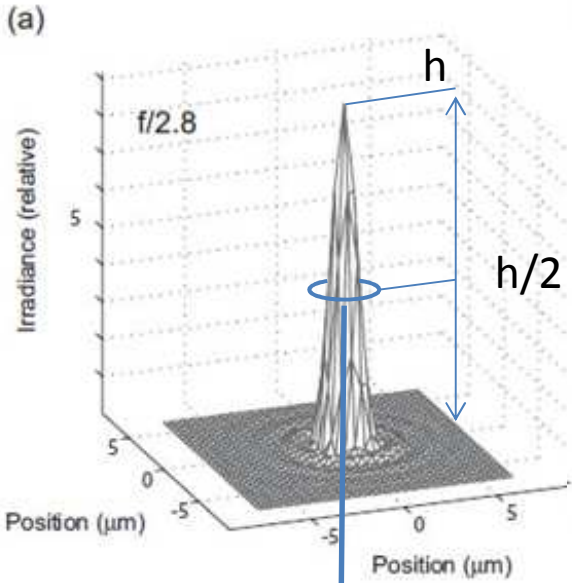
Pixel Size

Pixel size considerations

- Key issues are
 - matching the pixel size to the expected spot size from the optical system
 - understanding the relationship among pixel size , optics and rate at which signal builds

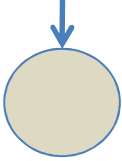
Optics and the Airy Disk:

Focal ratio: Sets spot size for diffraction limited optics

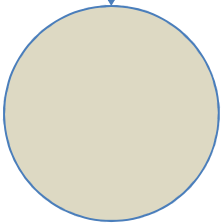


Airy Disk Diameter (microns)

Source: Catrysse



Airy Disk Diameter

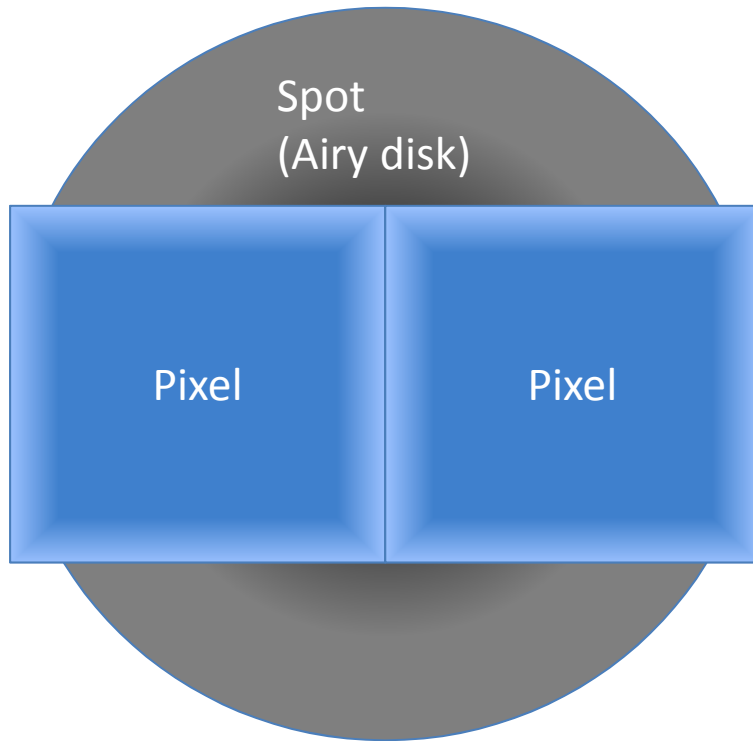


~3 microns, f/2.8

~10 microns, f/8.0

Nyquist Sampling of Airy Disk

Pixel Pitch: Sized to fit Airy Disk (spot):



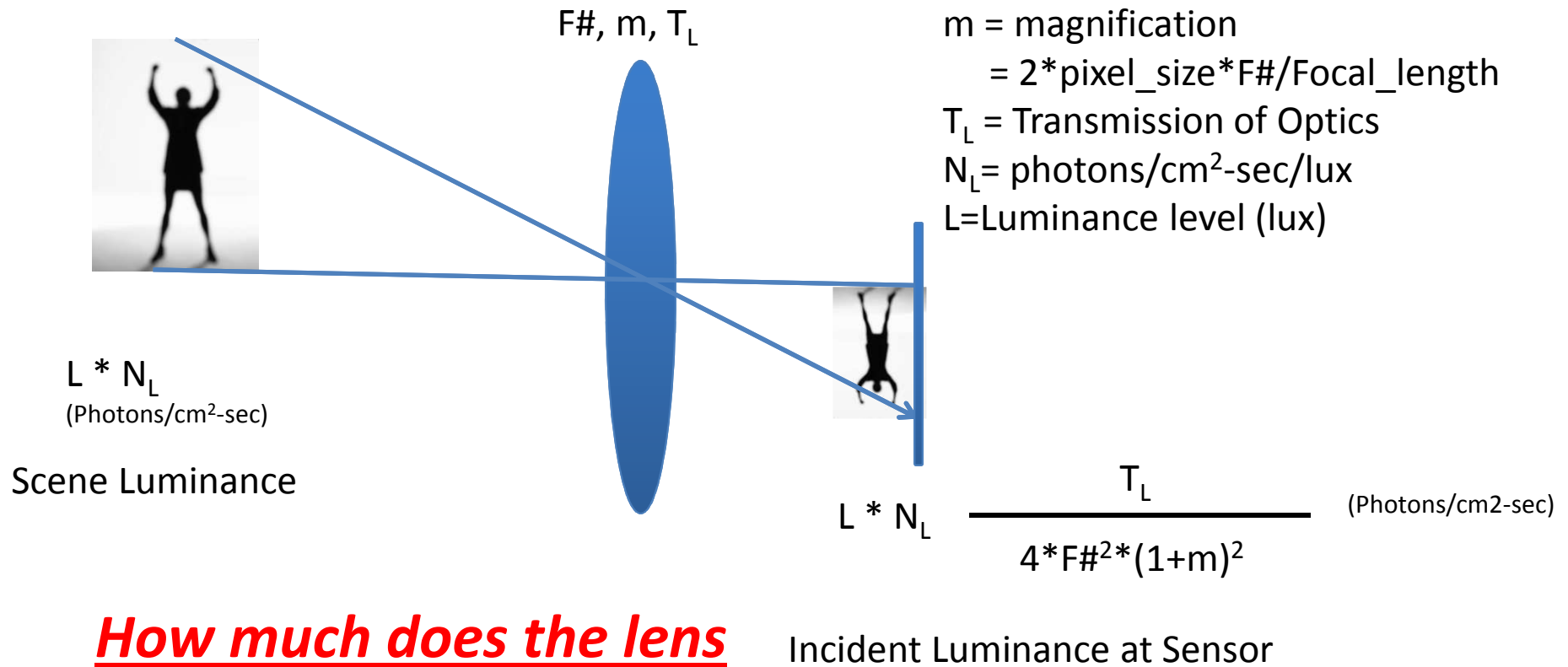
Nyquist Sampling Criteria:

$$\text{Pixel size} = 1.22 * \lambda * F\#$$

550 nm test wavelength				
Monochrome pixel size (microns)	Optimum F#	Optical		
		Airy Diameter resolution: (microns)	LP/mm	
0.75	1.12	1.5	667	
0.9	1.34	1.8	556	
1	1.49	2	500	
1.1	1.64	2.2	455	
1.25	1.86	2.5	400	
1.4	2.09	2.8	357	
1.5	2.24	3	333	
1.75	2.61	3.5	286	
2	2.98	4	250	
2.25	3.35	4.5	222	
2.5	3.73	5	200	
2.75	4.10	5.5	182	
3	4.47	6	167	
3.5	5.22	7	143	
4	5.96	8	125	
5	7.45	10	100	
5.4	8.05	10.8	93	
6	8.94	12	83	
6.8	10.13	13.6	74	
7.4	11.03	14.8	68	
9	13.41	18	56	
11	16.39	22	45	
12	17.88	24	42	
13.5	20.12	27	37	
18	26.83	36	28	
24	35.77	48	21	

- Exact Nyquist Sampling: 2 pixels to cover Airy Diameter (spot)

Delivering photons to the sensor: the impact of Imaging Lens F# and magnification



How much does the lens spread the light flux? (magnification)

Color or Monochrome

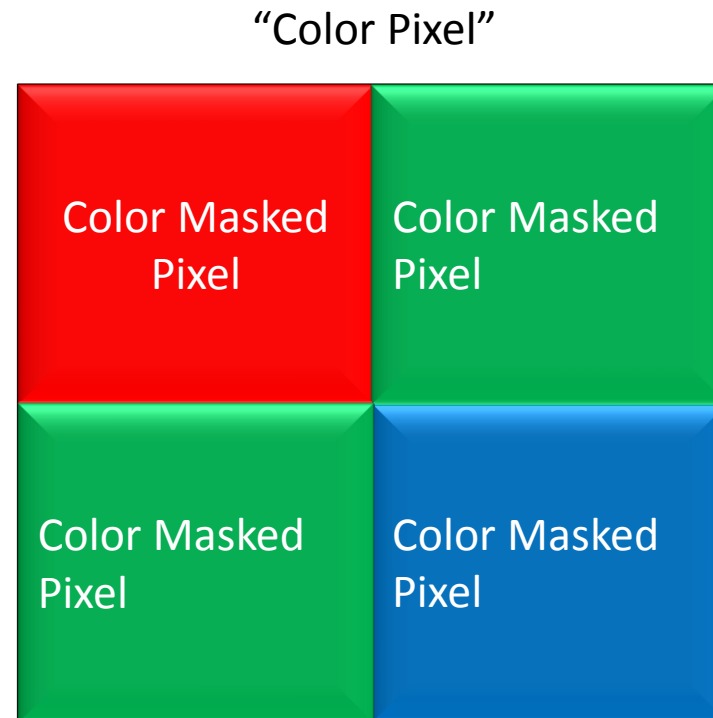
Monochrome or Color?

- Monochrome sensors have higher QE across the spectrum
- They can be used with filters, color or emission line, to make color images
- Require multiple sequential exposures through multiple filters to make color image
- Highest level of flexibility
- Transient and fast moving events such as Jupiter, Comets and Star Trails can present challenges for monochrome sensors; the object moves between filter changes
- Daytime/terrestrial color photography challenges
 - Need for filter changes with potential for motion in scene (trees moving etc)
- Color sensors can solve the transient event problem
- But have limitations:
 - Lower final image resolution than monochrome for a given photosite count
 - On chip Color Filter Array (CFA) typically leaks NIR, needs an IR-Cut filter. Typically those foul the red response for H α and [SII]
 - Extra image processing required: Must be deinterlaced and color interpolated to “fill in the missing data” (only $\frac{1}{2}$ of the green pixels are “real”, while $\frac{1}{4}$ of the red and blue pixels are “real”)
 - Less efficient to use with emission line filters

What changes for color imaging?

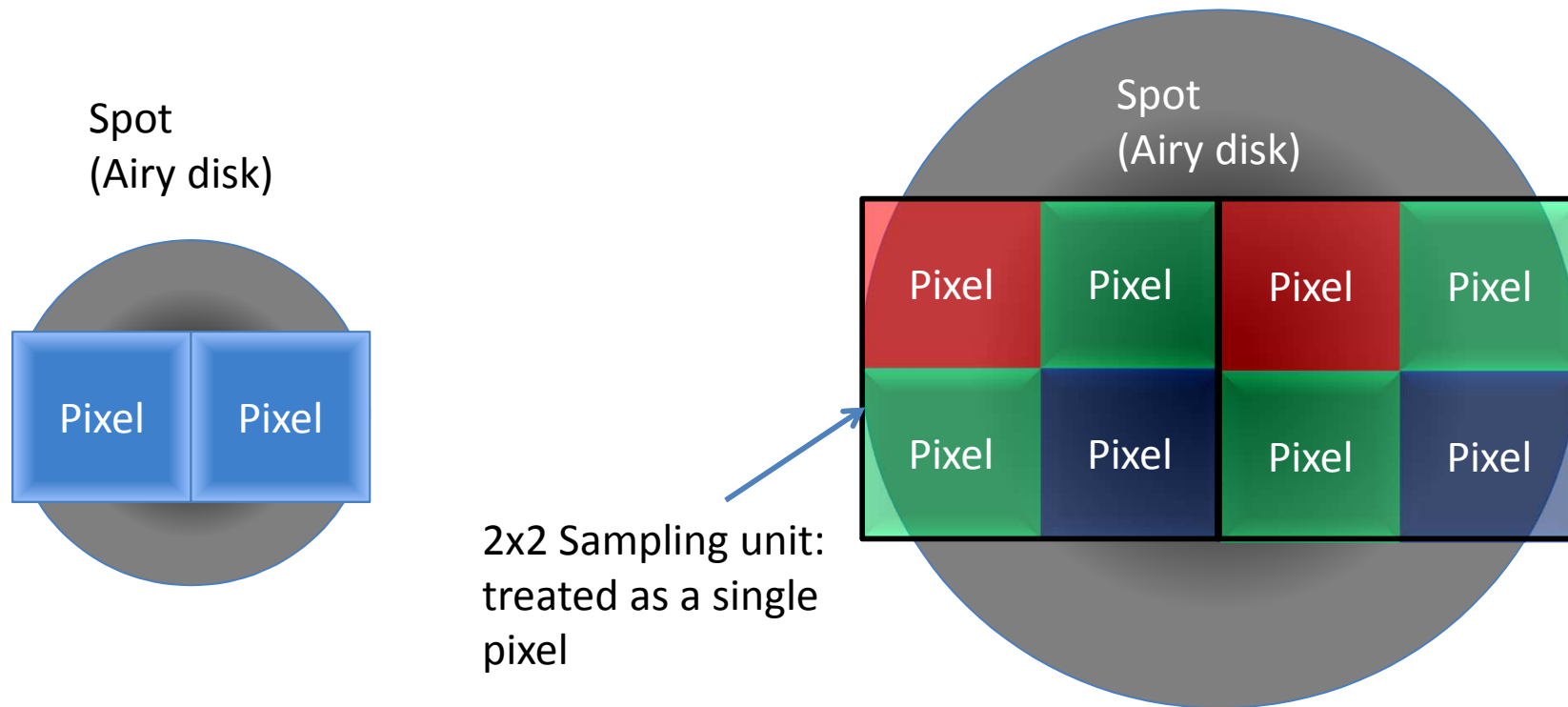


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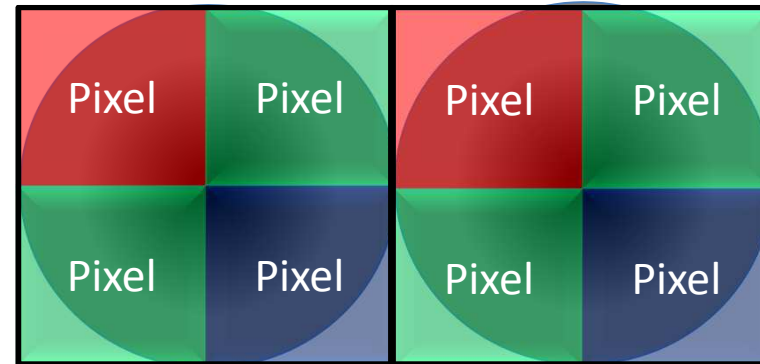
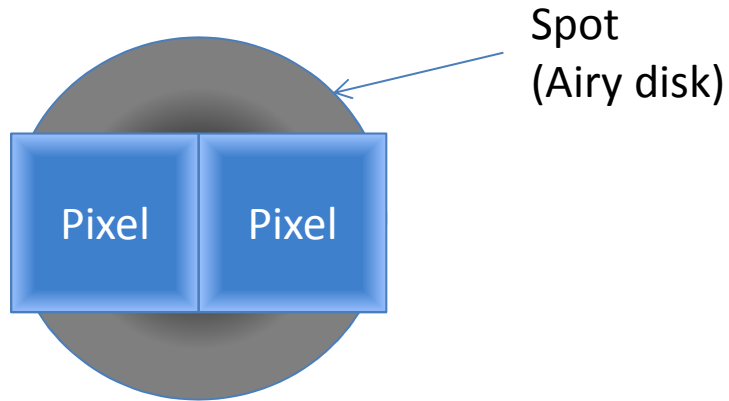
Marketing will call this four pixels
Sampling theory treats the four-
pixel unit as one pixel

Color Masked Pixels vs Monochrome Pixels: optimum spot size, F# changes



- **Same sensor base pixel size: different optimum spot size**
 - 2:1 difference in optimum F# when using color
 - 2:1 difference in LP/mm required by optics when using color

Color Masked Pixels used on same optics: Undersampled (resolution loss vs mono)



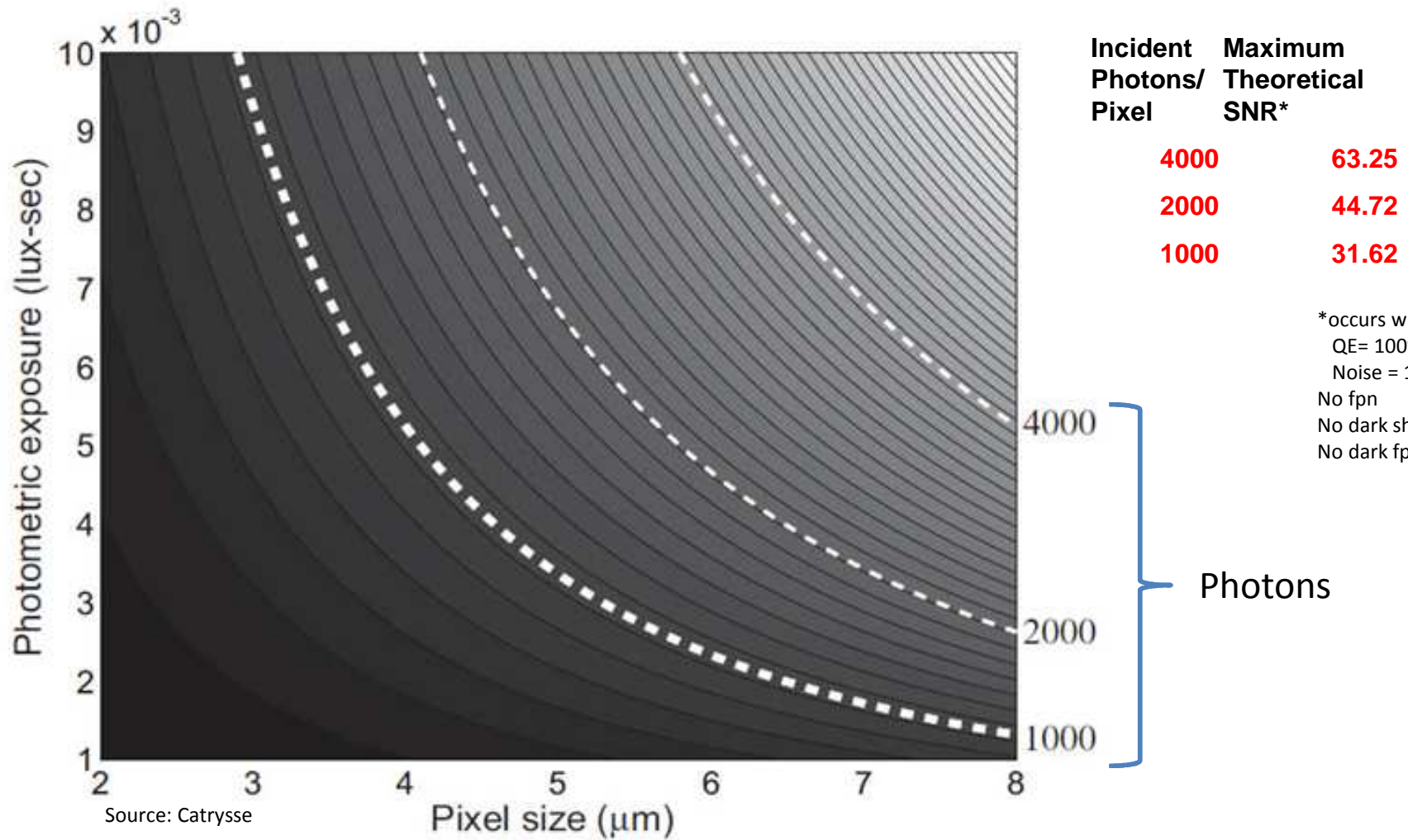
Color sequential monochrome



One shot color

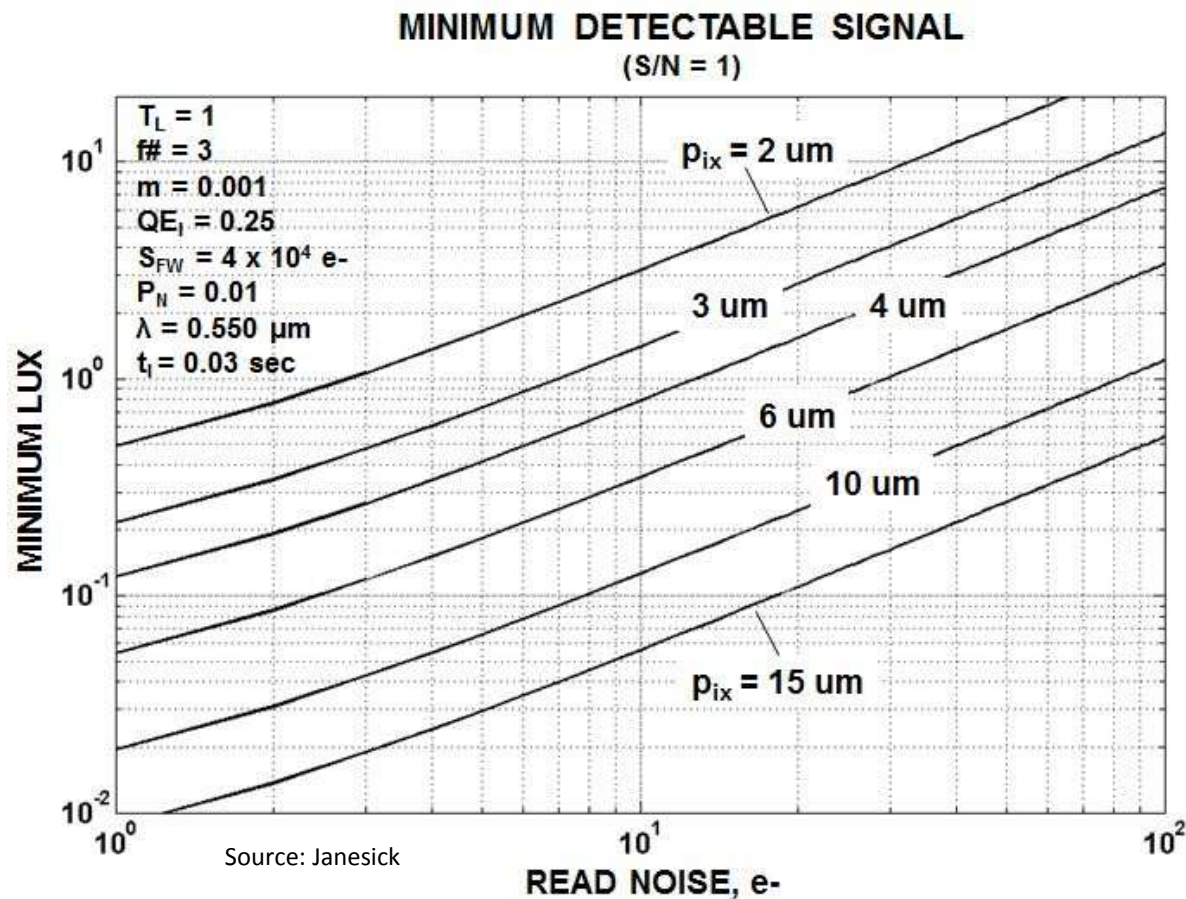
SNR considerations

Pixel Geometry: How many photons is your pixel receiving?



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Sensitivity vs Pixel size considering system noise impact



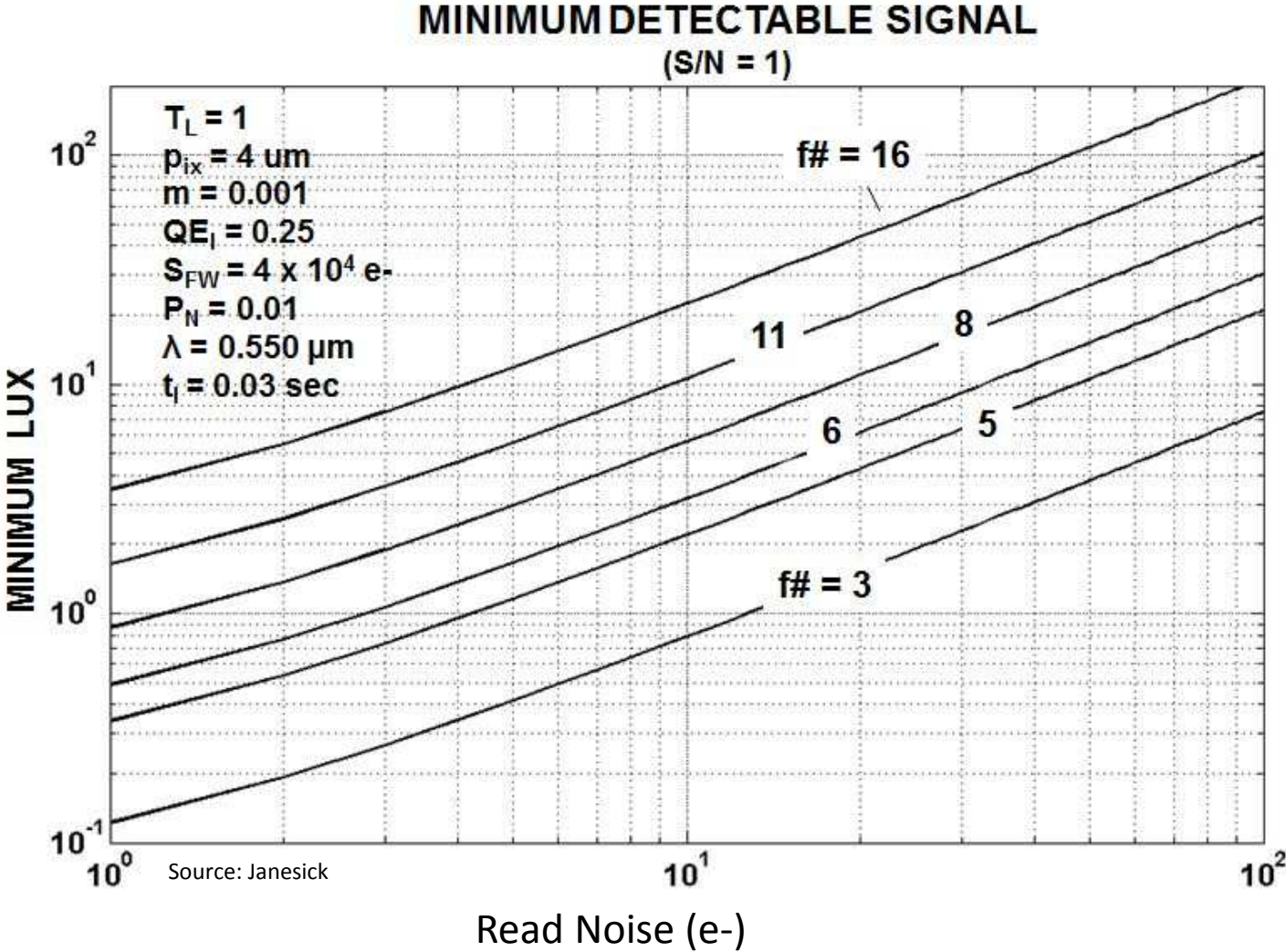
100% optical transmission
 f/3 optics
 Lens magnification of 0.001*
 QE = 25%
 Full well = 40Ke-
 PRNU = 1%
 550nm wavelength
 Exposure time = 30msec

* For magnification of 0.001,
 something that is 10 mm tall will fill
 a 10 micron pixel
 ie: a lens that makes a 10 x 10
 meter FOV fill a 1000 x 1000 pixel
 sensor with 10 micron pixel size

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F#, system noise impact

100% optical transmission
4 micron pixel
Lens magnification of 0.001*
QE = 25%
Full well = 40Ke-
PRNU = 1%
550nm wavelength
Exposure time = 30msec



preliminary